Space-Efficient Construction of Compressed Indexes in Deterministic Linear Time

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Abstract

We show that the compressed suffix array and the compressed suffix tree of a string T can be built in O(n) deterministic time using $O(n \log \sigma)$ bits of space, where n is the string length and σ is the alphabet size. Previously described deterministic algorithms either run in time that depends on the alphabet size or need $\omega(n \log \sigma)$ bits of working space. Our result has immediate applications to other problems, such as yielding the first deterministic linear-time LZ77 and LZ78 parsing algorithms that use $O(n \log \sigma)$ bits.

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1 Introduction

In the string indexing problem we pre-process a string T, so that for any query string P all occurrences of P in T can be found efficiently. Suffix trees and suffix arrays are two most popular solutions of this fundamental problem. A suffix tree is a compressed trie on suffixes of T; it enables us to find all occurrences of a string P in T in time O(|P| + occ) where occ is the number of times P occurs in T and |P| denotes the length of P. In addition to indexing, suffix trees also support a number of other, more sophisticated, queries. The suffix array of a string T is the lexicographically sorted array of its suffixes. Although suffix arrays do not support all queries that can be answered by the suffix tree, they use less space and are more popular in practical implementations. While the suffix tree occupies $O(n \log n)$ bits of space, the suffix array can be stored in $n \log n$ bits.

During the last twenty years there has been a significant increase in interest in compressed indexes, i.e., data structures that keep T in compressed form and support string matching queries. The compressed suffix array (CSA) [21, 14, 39] and the compressed suffix tree (CST) [40] are compressed counterparts of the suffix array and the suffix tree respectively. A significant part of compressed indexes relies on these two data structures or their variants. Both CSA and CST can be stored in $O(n \log \sigma)$ bits or less; we refer to e.g. [7] or [33] for an overview of compressed indexes.

It is well known that both the suffix array and the suffix tree can be constructed in O(n)time [30, 43, 44, 25]. The first algorithm that constructs the suffix tree in linear time independently of the alphabet size was presented by Farach [13]. There are also algorithms that directly construct the suffix array of T in O(n) time [24, 26]. If the (uncompressed) suffix tree is available, we can obtain CST and CSA in O(n) time. However this approach requires $O(n \log n)$ bits of working space. The situation is different if we want to construct compressed variants of these data structures using only $O(n \log \sigma)$ bits of space. Within this space the algorithm of Hon et al. [23] constructs the CST in $O(n \log^{\varepsilon} n)$ time for an arbitrarily small constant $\varepsilon > 0$. In the same paper the authors also showed that CSA can be constructed in $O(n \log \log \sigma)$ time. The algorithm of Okanohara and Sadakane constructs the CSA in linear time, but needs $O(n \log \sigma \log \log n)$ bits of space [37]. Belazzougui [2] described randomized algorithms that build both CSA and CST in O(n) time and $O(n \log \sigma)$ bits of space. His approach also provides deterministic algorithms with runtime $O(n \log \log \sigma)$ [3]. In this paper we show that randomization is not necessary in order to construct CSA and CST in linear time. Our algorithms run in O(n) deterministic time and require $O(n \log \sigma)$ bits of space.

Suffix trees, in addition to being an important part of many compressed indexes, also play an important role in many string algorithms. One prominent example is Lempel-Ziv parsing of a string using $O(n \log \sigma)$ bits. The best previous solutions for this problem either take $O(n \log \log \sigma)$ deterministic time or O(n) randomized time [27, 10]. For instance Köppl and Sadakane [27] showed how we can obtain LZ77- and LZ78-parsing for a string T in O(n) deterministic time and $O(n \log \sigma)$ bits, provided that the CST of T is constructed. Thus our algorithm, combined with their results, leads to the first linear-time deterministic LZ-parsing algorithm that needs $O(n \log \sigma)$ bits of space.

Overview. The main idea of our approach is the use of batch processing. Certain operations, such as rank and select queries on sequences, are a bottleneck of previous deterministic solutions. Our algorithms are divided into a large number of small tasks that can be executed independently. Hence, we can collect large batches of queries and answer all queries in a batch. This approach speeds up the computation because, as will be shown later, answering all queries in a batch takes less time than answering the same set of queries one-by-one. For example, our algorithm for generating the Burrows-Wheeler Transform of a text T works as follows. We cut the original text into slices

of $\Delta = \log_{\sigma} n$ symbols. The BWT sequence is constructed by scanning all slices in the right-to-left order. All slices are processed at the same time. That is, the algorithm works in Δ steps and during the j-th step, for $0 \le j \le \Delta - 1$, we process all suffixes that start at position $i\Delta - j - 1$ for all $1 \leq i \leq n/\Delta$. Our algorithm maintains the sorted list of suffixes and keeps information about those suffixes in a symbol sequence B. For every suffix $S_i = T[i\Delta - j - 1..]$ processed during the step j, we must find its position in the sorted list of suffixes. Then the symbol $T[i\Delta - j - 2]$ is inserted at the position that corresponds to S_i in B. Essentially we can find the position of every new suffix S_i by answering a rank query on the sequence B. Details are given in Section 2. Next we must update the sequence by inserting the new symbols into B. Unfortunately we need $\Omega(\log n / \log \log n)$ time in general to answer rank queries on a dynamic sequence [17]. Even if we do not have to update the sequence, we need $\Omega(\log \log \sigma)$ time to answer a rank query [8]. In our case, however, the scenario is different: There is no need to answer queries one-by-one. We must provide answers to a large *batch* of n/Δ rank queries with one procedure. In this paper we show that the lower bounds for rank queries can be circumvented in the batched scenario: we can answer the batch of queries in $O(n/\Delta)$ time, i.e., in constant time per query. We also demonstrate that a batch of n/Δ insertions can be processed in $O(n/\Delta)$ time. This result is of independent interest.

Data structures that answer batches of rank queries and support batched updates are described in Sections 3, A.2, and A.3. This is the most technically involved aspect of our result. In Section 3 we show how answers to a large batch of queries can be provided. In Section A.2 we describe a special labeling scheme that assigns monotonously increasing labels to elements of a list. We conclude this portion in Section A.3 where we show how the static data structure can be dynamized. Next we turn to the problem of constructing the compressed suffix tree. First we describe a data structure that answers partial rank queries in constant time and uses $O(n \log \log \sigma)$ additional bits in Section A.4; unlike previous solutions, our data structure can be constructed in O(n) deterministic time. This result is plugged into the algorithm of Belazzougui [2] to obtain the suffix tree topology in O(n)deterministic time. Finally we show how the permuted LCP array (PLCP) can be constructed in O(n) time, provided we already built the suffix array and the suffix tree topology; the algorithm is described in Section 5. Our algorithm for constructing PLCP is also based on batch processing of rank queries. To make this paper self-contained we provide some background on compressed data structures and indexes in Section A.1.

We denote by T[i..] the suffix of T starting at position i and we denote by T[i..j] the substring of T that begins with T[i] and ends with T[j], $T[i..] = T[i]T[i + 1] \dots T[n - 1]$ and T[i..j] = $T[i]T[i + 1] \dots T[j - 1]T[j]$. We assume that the text T ends with a special symbol \$\$ and \$\$ lexicographically precedes all other symbols in T. The alphabet size is σ and symbols are integers in $[0..\sigma - 1]$ (so \$ corresponds to 0). In this paper, as in the previous papers on this topic, we use the word RAM model of computation. A machine word consists of log n bits and we can execute standard bit operations, addition and subtraction in constant time. We will assume for simplicity that the alphabet size $\sigma \leq n^{1/4}$. This assumption is not restrictive because for $\sigma > n^{1/4}$ linear-time algorithms that use $O(n \log \sigma) = O(n \log n)$ bits are already known.

2 Linear Time Construction of the Burrows-Wheeler Transform

In this section we show how the Burrows-Wheeler transform (BWT) of a text T can be constructed in O(n) time using $O(n \log \sigma)$ bits of space. Let $\Delta = \log_{\sigma} n$. We can assume w.l.o.g. that the text length is divisible by Δ (if this is not the case we can pad the text T with $\lceil n/\Delta \rceil \Delta - n$ \$-symbols). The BWT of T is a sequence B defined as follows: if T[k..] is the (i+1)-th lexicographically smallest suffix, then $B[i] = T[k-1]^1$. Thus the symbols of B are the symbols that precede the suffixes of T, sorted in lexicographic order. We will say that T[k-1] represents the suffix T[k..] in B. Our algorithm divides the suffixes of T into Δ classes and constructs B in Δ steps. We say that a suffix S is a *j*-suffix for $0 \le j < \Delta$ if $S = T[i\Delta - j - 1..]$ for some *i*, and denote by S_j the set of all *j*-suffixes, $S_j = \{T[i\Delta - j - 1..] \mid 1 \le i \le n/\Delta\}$. During the *j*-th step we process all *j*-suffixes and insert symbols representing *j*-suffixes at appropriate positions of the sequence B.

Steps 0-1. We sort suffixes in S_0 and S_1 by constructing a new text and representing it as a sequence of n/Δ meta-symbols. Let $T_1 = T[n-1]T[0]T[1] \dots T[n-2]$ be the text T rotated by one symbol to the right and let $T_2 = T[n-2]T[n-1]T[0] \dots T[n-3]$ be the text obtained by rotating T_1 one symbol to the right. We represent T_1 and T_2 as sequences of length n/Δ over meta-alphabet σ^{Δ} (each meta-symbol corresponds to a string of length Δ). Thus we view T_1 and T_2 as

$$T_1 = \boxed{T[n-1]\dots T[\Delta-2]} \boxed{T[\Delta-1]\dots T[2\Delta-2]} \boxed{T[2\Delta-1]\dots T[3\Delta-2]} \boxed{T[3\Delta-1]\dots}\dots$$
$$T_2 = \boxed{T[n-2]\dots T[\Delta-3]} \boxed{T[\Delta-2]\dots T[2\Delta-3]} \boxed{T[2\Delta-2]\dots T[3\Delta-3]} \boxed{T[3\Delta-2]\dots}\dots$$

Let $T_3 = T_1 \circ T_2$ denote the concatenation of T_1 and T_2 . To sort the suffixes of T_3 , we sort the meta-symbols of T_3 and rename them with their ranks. Since meta-symbols correspond to $(\log n)$ -bit integers, we can sort them in time O(n) using radix sort. Then we apply a linear-time and linear-space suffix array construction algorithm [24] to T_3 . We thus obtain a sorted list of suffixes L for the meta-symbol sequence T_3 . Suffixes of T_3 correspond to the suffixes from $S_0 \cup S_1$ in the original text T: the suffix $T[i\Delta - 1..]$ corresponds to the suffix of S_0 starting with metasymbol $T[i\Delta - 1]T[i\Delta]...$ in T_3 and the suffix $T[i\Delta - 2...]$ corresponds to the suffix of S_1 starting with $T[i\Delta - 2]T[i\Delta - 1]...$. Since we assume that the special symbol \$ is smaller than all other symbols, this correspondence is order-preserving. Hence by sorting the suffixes of T_3 we obtain the sorted list L' of suffixes in $S_0 \cup S_1$. Now we are ready to insert symbols representing j-suffixes into B: Initially B is empty. Then the list L' is traversed and for every suffix T[k..] that appears in L' we add the symbol T[k-1] at the end of B.

When suffixes in S_0 and S_1 are processed, we need to record some information for the next step of our algorithm. For every suffix $S \in S_1$ we keep its position in the sorted list of suffixes. The position of suffix $T[i\Delta - 2..]$ is stored in the entry W[i] of an auxiliary array W, which at the end of the *j*-th step will contain the positions of the suffixes $T[i\Delta - j - 1..]$. We also keep an auxiliary array Acc of size σ : Acc[a] is equal to the number of occurrences of symbols $i \leq a - 1$ in the current sequence B.

Step j for $j \ge 2$. Suppose that suffixes from S_0, \ldots, S_{j-1} are already processed. The symbols that precede suffixes from these sets are stored in the sequence B; the k-th symbol B[k] in B is the symbol that precedes the k-th lexicographically smallest suffix from $\bigcup_{t=0}^{j-1} S_t$. For every suffix $T[i\Delta - j..]$, we know its position W[i] in B. Every suffix $S_i = T[i\Delta - j - 1..] \in S_j$ can be represented as $S_i = aS'_i$ for some symbol a and the suffix $S'_i = T[i\Delta - j..] \in S_{j-1}$. We look up the position $t_i = W[i]$ of S'_i and answer rank query $r_i = \operatorname{rank}_a(t_i, B)$. We need $\Omega(\log \frac{\log \sigma}{\log \log n})$ time to answer a single rank query on a static sequence [8]. If updates are to be supported, then we need $\Omega(\log n/\log \log n)$ time to answer such a query [17]. However in our case the scenario is different:

¹So B[0] has the lexicographically smallest suffix (i+1=1) and so on. The exact formula is $B[i] = T[(k-1) \mod n]$. We will write B[i] = T[k-1] to avoid tedious details.

we perform a *batch* of n/Δ queries to sequence B, i.e., we have to find r_i for all t_i . During Step 2 the number of queries is equal to |B|/2 where |B| denotes the number of symbols in B. During step j the number of queries is $|B|/j \ge |B|/\Delta$. We will show in Section 3 that such a large batch of rank queries can be answered in O(1) time per query. Now we can find the rank p_i of S_i among $\bigcup_{t=1}^{j} S_t$: there are exactly p_i suffixes in $\bigcup_{t=1}^{j} S_t$ that are smaller than S_i , where $p_i = Acc[a] + r_i$. Correctness of this computation can be proved as follows.

Proposition 1 Let $S_i = aS'_i$ be an arbitrary suffix from the set S_j . For every occurrence of a symbol a' < a in the sequence B, there is exactly one suffix $S_p < S_i$ in $\bigcup_{t=1}^j S_t$, such that S_p starts with a'. Further, there are exactly r_i suffixes S_v in $\bigcup_{t=1}^j S_t$ such that $S_v \leq S_i$ and S_v starts with a.

Proof: Suppose that a suffix S_p from S_t , such that $j \ge t \ge 1$, starts with a' < a. Then $S_p = a'S'_p$ for some $S'_p \in \mathcal{S}_{t-1}$. By definition of the sequence B, there is exactly one occurrence of a' in B for every such S'_p . Now suppose that a suffix $S_v \in \mathcal{S}_t$, such that $j \ge t \ge 1$, starts with a and $S_v \le S_i$. Then $S_v = aS'_v$ for $S'_v \in \mathcal{S}_{t-1}$ and $S'_v \le S'_i$. For every such S'_v there is exactly one occurrence of the symbol a in $B[1..t_i]$, where t_i is the position of S'_i in B.

The above calculation did not take into account the suffixes from S_0 . We compute the number of suffixes $S_k \in S_0$ such that $S_k < S_i$ using the approach of Step 0 - 1. Let T_1 be the text obtained by rotating T one symbol to the right. Let T' be the text obtained by rotating $T \ j + 1$ symbols to the right. We can sort suffixes of S_0 and S_j by concatenating T_1 and T', viewing the resulting text T'' as a sequence of $2n/\Delta$ meta-symbols and constructing the suffix array for T''. When suffixes in $S_0 \cup S_j$ are sorted, we traverse the sorted list of suffixes; for every suffix $S_i \in S_j$ we know the number q_i of lexicographically smaller suffixes from S_0 .

We then modify the sequence B: We sort new suffixes S_i by $o_i = p_i + q_i$. Next we insert the symbol $T[i\Delta - j - 1]$ at position $o_i - 1$ in B (assuming the first index of B is B[0]); insertions are performed in increasing order of o_i . We will show that this procedure also takes O(1) time per update for a large batch of insertions. Finally we record the position of every new suffix from S_j in the sequence B. Since the positions of suffixes from S_{j-1} are not needed any more, we use the entry W[i] of W to store the position of $T[i\Delta - j - 1..]$. The array Acc is also updated.

When Step $\Delta - 1$ is completed, the sequence *B* contains *n* symbols and *B*[*i*] is the symbol that precedes the (i+1)-th smallest suffix of *T*. Thus we obtained the BWT of *T*. Step 0 of our algorithm uses $O((n/\Delta) \log n) = O(n \log \sigma)$ bits. For all the following steps we need to maintain the sequence *B* and the array *W*. *B* uses $O(\log \sigma)$ bits per symbol and *W* needs $O((n/\Delta) \log n) = O(n \log \sigma)$ bits. Hence our algorithm uses $O(n \log \sigma)$ bits of workspace. Procedures for querying and updating *B* are described in the following section. Our result can be summed up as follows.

Theorem 1 Given a string T[0..n-1] over an alphabet of size σ , we can construct the BWT of T in O(n) deterministic time using $O(n \log \sigma)$ bits.

3 Batched Rank Queries on a Sequence

In this section we show how a batch of m rank queries for $\frac{n}{\log^2 n} \leq m \leq n$ can be answered in O(m) time on a sequence B of length n. We start by describing a static data structure. A data structure that supports batches of queries and batches of insertions will be described later. We will assume $\sigma \geq \log^4 n$; if this is not the case, the data structure from [15] can be used to answer rank queries in time O(1).

Following previous work [19], we divide B into chunks of size σ (except for the last chunk that contains at most σ symbols). For every symbol a we keep a binary sequence $M_a = 1^{d_1} 0 1^{d_2} 0 \dots 1^{d_f}$ where f is the total number of chunks and d_i is the number of occurrences of a in the chunk. We keep the following information for every chunk C. Symbols in a chunk C are represented as pairs (a, i): we store a pair (a, i) if and only if C[i] = a. These pairs are sorted by symbols and pairs representing the same symbol a are sorted by their positions in C; all sorted pairs from a chunk are kept in a sequence R. The array F consists of σ entries; F[a] contains a pointer to the first occurrence of a symbol a in R (or null if a does not occur in C). Let R_a denote the subsequence of R that contains all pairs (a, \cdot) for some symbol a. If R_a contains at least $\log^2 n$ pairs, we split R_a into groups $H_{a,r}$ of size $\Theta(\log^2 n)$. For every group, we keep its first pair in the sequence R'. Thus R' is also a subsequence of R. For each pair (a', i') in R' we also store the partial rank of C[i'] in C, rank_{C[i']}<math>(i', C).</sub>

All pairs in $H_{a,r}$ are kept in a data structure $D_{a,r}$ that contains the second components of pairs $(a,i) \in H_{a,r}$. Thus $D_{a,r}$ contains positions of $\Theta(\log^2 n)$ consecutive symbols a. If R_a contains less than $\log^2 n$ pairs, then we keep all pairs starting with symbol a in one group $H_{a,0}$. Every $D_{a,r}$ contains $O(\log^2 n)$ elements. Hence we can implement $D_{a,r}$ so that predecessor queries are answered in constant time: for any integer q, we can find the largest $x \in H_{a,r}$ satisfying $x \leq q$ in O(1) time [18]. We can also find the number of elements $x \in H_{a,r}$ satisfying $x \leq q$ in O(1) time. This operation on $H_{a,r}$ can be implemented using bit techniques similar to those suggested in [35]; details are to be given in the full version of this paper.

Queries on a Chunk. Now we are ready to answer a batch of queries in O(1) time per query. First we describe how queries on a chunk can be answered. Answering a query $\operatorname{rank}_a(i, C)$ on a chunk C is equivalent to counting the number of pairs (a, j) in R such that $j \leq i$. Our method works in three steps. We start by sorting the sequence of all queries on C. Then we "merge" the sorted query sequence with R'. That is, we find for every $\operatorname{rank}_a(i, C)$ the rightmost pair (a, j') in R', such that $j' \leq i$. Pair (a, j') provides us with an approximate answer to $\operatorname{rank}_a(i, C)$ (up to an additive $O(\log^2 n)$ term). Then we obtain the exact answer to each query by searching in some data structure $D_{a,j}$. Since $D_{a,j}$ contains only $O(\log^2 n)$ elements, the search can be completed in O(1) time. A more detailed description follows.

Suppose that we must answer v queries $\operatorname{rank}_{a_1}(i_1, C)$, $\operatorname{rank}_{a_2}(i_2, C)$, ..., $\operatorname{rank}_{a_v}(i_v, C)$ on a chunk C. We sort the sequence of queries by pairs (a_i, i_j) in increasing order. This sorting step takes $O(\sigma/\log^2 n + v)$ time, where v is the number of queries: if $v < \sigma/\log^3 n$, we sort in $O(v \log n) = O(\sigma / \log^2 n)$ time; if $v \ge \sigma / \log^3 n$, we sort in O(v) time using radix sort (e.g., with radix $\sqrt{\sigma}$). Then we simultaneously traverse the sorted sequence of queries and R'; for each query pair (a_i, i_i) we identify the pair (a_t, p_t) in R' such that either (i) $p_t \leq i_i \leq p_{t+1}$ and $a_i = a_t = a_{t+1}$ or (ii) $p_t \leq i_j$, $a_j = a_t$, and $a_t \neq a_{t+1}$. That is, we find the largest $p_t \leq i_j$ such that $(a_j, p_t) \in R'$ for every query pair (a_j, i_j) . If (a_t, p_t) is found, we search in the group H_{a_t, p_t} that starts with the pair (a_t, p_t) . If the symbol a_j does not occur in R', then we search in the leftmost group $H_{a_j,0}$. Using D_{a_t,p_t} (resp. $D_{a_t,0}$), we find the largest position $x_t \in H_{a_t,p_t}$ such that $x_t \leq i_j$. Thus x_t is the largest position in C satisfying $x_t \leq i_j$ and $C[x_t] = a_j$. We can then compute rank_{$a_t}(x_t, C)$ as</sub> follows: Let n_1 be the partial rank of $C[p_t]$, $n_1 = \operatorname{rank}_{C[p_t]}(p_t, C)$. Recall that we explicitly store this information for every position in R'. Let n_2 be the number of positions $i \in H_{a_t,p_t}$ satisfying $i \leq x_t$. We can compute n_2 in O(1) time using D_{a_t,p_t} . Then $\operatorname{rank}_{a_i}(x_t,C) = n_1 + n_2$. Since $C[x_t]$ is the rightmost occurrence of a_i up to $C[i_i]$, $\operatorname{rank}_{a_i}(i_i, C) = \operatorname{rank}_{a_i}(x_t, C)$. The time needed to traverse the sequence R' is $O(\sigma/\log^2 n)$ for all the queries. Other computations take O(1) time per query. Hence the sequence of v queries on a chunk is answered in $O(v + \sigma/\log^2 n)$ time.

Global Sequence. Now we consider the global sequence of queries $\operatorname{rank}_{a_1}(i_1, B), \ldots, \operatorname{rank}_{a_m}(i_m, B)$. First we assign queries to chunks (e.g., by sorting all queries by $(\lfloor i/\sigma \rfloor + 1)$ using radix sort). We answer the batch of queries on the *j*-th chunk in $O(m_j + \sigma/\log^2 n)$ time where m_j is the number of queries on the *j*-th chunk. Since $\sum m_j = m$, all *m* queries are answered in $O(m+n/\log^2 n) = O(m)$ time. Now we know the rank $n_{j,2} = \operatorname{rank}_{a_j}(i'_j, C)$, where $i'_j = i_j - \lfloor i/\sigma \rfloor \sigma$ is the relative position of $B[i_j]$ in its chunk *C*.

The binary sequences M_a allows us reduce rank queries on B to rank queries on a chunk C. All sequences M_a contain $n + \lfloor n/\sigma \rfloor \sigma$ bits; hence they use O(n) bits of space. We can compute the number of occurrences of a in the first j chunks in O(1) time by answering one select query. Consider a rank query $\operatorname{rank}_{a_j}(i_j, B)$ and suppose that $n_{j,2}$ is already known. We compute $n_{j,1}$, where $n_{j,1} = \operatorname{select}_0(\lfloor i_j/\sigma \rfloor, M_{a_j}) - \lfloor i_j/\sigma \rfloor$ is the number of times a_j occurs in the first $\lfloor i_j/\sigma \rfloor$ chunks. Then we compute $\operatorname{rank}_{a_j}(i_j, B) = n_{j,1} + n_{j,2}$.

Theorem 2 We can keep a sequence B[0..n-1] over an alphabet of size σ in $O(n \log \sigma)$ bits of space so that a batch of m rank queries can be answered in O(m) time, where $\frac{n}{\log^2 n} \leq m \leq n$.

The static data structure of Theorem 2 can be dynamized so that batched queries and batched insertions are supported. Our dynamic data structures supports a batch of m queries in time O(m) and a batch of m insertions in amortized time O(m) for any m that satisfies $\frac{n}{\log_{\sigma} n} \leq m \leq n$. We describe the dynamic data structure in Sections A.2 and A.3.

4 Building the Suffix Tree

Belazzougui proved the following result [2]: if we are given the BWT B of a text T and if we can report all the distinct symbols in a range of B in optimal time, then in O(n) time we can: (i) enumerate all the suffix array intervals corresponding to internal nodes of the suffix tree and (ii) for every internal node list the labels of its children and their intervals. Further he showed that, if we can enumerate all the suffix tree intervals in O(n) time, then we can build the suffix tree topology [40] in O(n) time. The algorithms need only O(n) additional bits of space. We refer to Lemmas 4 and 1 and their proofs in [2] for details.

In Section A.4 we show that a partial rank data structure can be built in O(n) deterministic time. This can be used to build the desired structure that reports the distinct symbols in a range, in O(n) time and using $O(n \log \log \sigma)$ bits. The details are given in Section A.5. Therefore, we obtain the following result.

Lemma 1 If we already constructed the BWT of a text T, then we can build the suffix tree topology in O(n) time using $O(n \log \log \sigma)$ additional bits.

In Section 5 we show that the permuted LCP array of T can be constructed in O(n) time using $O(n \log \sigma)$ bits of space. Thus we obtain our main result on building compressed suffix trees.

Theorem 3 Given a string T[0..n-1] over an alphabet of size σ , we can construct the compressed suffix tree of T in O(n) deterministic time using $O(n \log \sigma)$ additional bits.

5 Constructing the Permuted LCP Array

The permuted LCP array is defined as PLCP[i] = j if and only if SA[r] = i and the longest common prefix of T[SA[r]..] and T[SA[r-1]..] is of length j. In other words PLCP[i] is the length of the longest common prefix of T[i..] and the suffix that precedes it in the lexicographic ordering. In this section we show how the permuted LCP array PLCP[0..n-1] can be built in linear time.

Preliminaries. For i = 0, 1, ..., n let $\ell_i = PLCP[i]$. It is easy to observe that $\ell_i \leq \ell_{i+1} + 1$: if the longest common prefix of T[i..] and T[j..] is q, then the longest common prefix of T[i + 1..]and T[j + 1..] is at least q - 1. Let $\Delta' = \Delta \log \log \sigma$ for $\Delta = \log_{\sigma} n$. By the same argument $\ell_i \leq \ell_{i+\Delta'} + \Delta'$. To simplify the description we will further assume that $\ell_{-1} = 0$. It can also be shown that $\sum_{i=0}^{n-1} (\ell_i - \ell_{i-1}) = O(n)$.

We will denote by B the BWT sequence of T; \overline{B} denotes the BWT of the reversed text $\overline{T} = T[n-1]T[n-2]...T[1]T[0]$. Let p be a factor (substring) of T and let c be a character. The operation extendright(p,c) computes the suffix interval of pc in B and the suffix interval of \overline{pc} in \overline{B} provided that the intervals of p and \overline{p} are known. The operation contractleft(cp) computes the suffix intervals of factors cp and \overline{cp} are known². It was demonstrated [42, 5] that both operations can be supported by answering O(1) rank queries on B and \overline{B} .

Belazzougui [2] proposed the following algorithm for consecutive computing of $\ell_0, \ell_1, \ldots, \ell_n$. Suppose that ℓ_{i-1} is already known. We already know the rank r_{i-1} of T[i-1..], the interval of $T[i-1..i + \ell_{i-1} - 1]$ in \overline{B} . We compute the rank r_i of T[i..]. If $r_{i-1} - 1$ is known, we can compute r_i in O(1) time by answering one select query on B; see Section A.1. Then we find the interval $[r_s, r_e]$ of $T[i..i + \ell_{i-1} - 1]$ in \overline{B} and the interval $[r'_s, r'_e]$ of $\overline{T[i..i + \ell_{i-1} - 1]}$ in \overline{B} . These two intervals can be computed by contractleft. In the special case when i = 0 or $\ell_{i-1} = 0$, we set $[r_s, r_e] = [r'_s, r'_e] = [0, n-1]$. Then for $j = 1, 2, \ldots$ we find the intervals for $T[i..i + (\ell_{i-1} - 1) + j]$ and $\overline{T[i..i + (\ell_{i-1} - 1) + j]}$. Every following pair of intervals is found by operation extendright. We stop when the interval of $T[i..i + \ell_{i-1} - 1 + j]$ is $[r_{s,j}, r_{e,j}]$ such that $r_{s,j} = r_i$. For all j', such that $0 \le j' < j$, we have $r_{s,j'} < r_i$. It can be shown that $\ell_i = \ell_{i-1} + j - 1$; see the proof of [2, Lemma 2]. Once ℓ_i is computed, we increment i and find the next ℓ_i in the same way. All ℓ_i are computed by O(n) contractleft and extendright operations.

Implementing contractleft and extendright. We create the succinct representation of the suffix tree topology both for T and \overline{T} ; they will be denoted by \mathcal{T} and $\overline{\mathcal{T}}$ respectively. We keep both B and \overline{B} in the data structure that supports access in O(1) time. We also store B in the data structure that answers select queries in O(1) time. The array Acc keeps information about accumulated frequencies of symbols: Acc[i] is the number of occurrences of all symbols $a \leq i - 1$ in B. Operation contractleft is implemented as follows. Suppose that we know the interval [i, j] for a factor cp and the interval [i', j'] for the factor \overline{cp} . We can compute the interval $[i_1, j_1]$ of p by finding $l = \text{select}_c(i - Acc[c], B)$ and $r = \text{select}_c(j - Acc[c], B)$. Then we find the lowest common ancestor x of leaves l and r in the suffix tree \mathcal{T} . We set $i_1 = \text{leftmost_leaf}(x)$ and $j_1 = \text{rightmost_leaf}(x)$. Then we consider the number of distinct symbols in $B[i_1...j_1]$. If c is the only symbol that occurs in $B[i_1...j_1]$, then all factors p in T are preceded by c. Hence all factors p in \overline{T} are followed by c and $[i'_1, j'_1] = [i', j']$. Otherwise we find the lowest common ancestor y of leaves i' and j' in $\overline{\mathcal{T}}$. Then we identify y' = parent(y) in $\overline{\mathcal{T}}$ and let $i'_1 = \text{leftmost_leaf}(y')$ and $j'_1 = \text{rightmost_leaf}(y')$. Thus contractleft can be supported in O(1) time.

²Throughout this paper reverse strings are overscored. Thus \overline{p} and \overline{pc} are reverse strings of p and pc respectively.

Now we consider the operation extendright. Suppose that [i, j] and [i', j'] are intervals of p and \overline{p} in B and \overline{B} respectively. We compute the interval of \overline{pc} by using the standard BWT machinery. Let $i'_1 = \operatorname{rank}_c(i'-1,\overline{B}) + Acc[c]$ and $j'_1 = \operatorname{rank}_c(j',\overline{B}) + Acc[c] - 1$. We check whether c is the only symbol in $\overline{B}[i'..j']$. If this is the case, then all occurrences of \overline{p} in \overline{T} are preceded by c and all occurrences of p in T are followed by c. Hence the interval of pc in B is $[i_1, j_1] = [i, j]$. Otherwise there is at least one other symbol besides c that can follow p. Let x denote the lowest common ancestor of leaves i and j. If y is the child of x that is labeled with c, then the interval of pc is $[i_1, j_1]$ where $i_1 = \operatorname{leftmost_leaf}(y)$ and $j_1 = \operatorname{rightmost_leaf}(y)$.

We can find the child y of x that is labeled with c by answering rank and select queries on two additional sequences, L and D. The sequence L contains labels of children for all nodes of \mathcal{T} ; labels are ordered by nodes and labels of the same node are ordered lexicographically. We encode the degrees of all nodes in a sequence $D = 1^{d_1} 0 1^{d_2} 0 \dots 1^{d_n}$, where d_i is the degree of the *i*-th node. We compute $v = \text{select}_0(x, D) - x$, $p_1 = \text{rank}_c(v, L)$, $p_2 = \text{select}_c(p_1 + 1, L)$, and $j = p_2 - v$. Then y is the *j*-th child of x. The bottleneck of **extendright** are the computations of p_1 , i'_1 , and j'_1 because we need $\Omega(\log \frac{\log \sigma}{\log \log n})$ time to answer a rank query on L (resp. on \overline{B}); all other calculations can be executed in O(1) time.

Our Approach. Our algorithm follows the technique of [2] that relies on operations extendright and contractleft for building the PLCP. We implement these two operations as described above; hence we will have to perform $\Theta(n)$ rank queries on sequences L and \overline{B} . Our method creates large batches of queries; each query in a batch is answered in O(1) time using Theorem 2.

During the pre-processing stage we create the machinery for supporting operations extendright and contractleft. We compute the BWT B of T and the BWT \overline{B} for the reverse text \overline{T} . We also construct the suffix tree topologies \mathcal{T} and $\overline{\mathcal{T}}$. When B is constructed, we record the positions in B that correspond to suffixes $T[i \cdot \Delta'..]$ for $i = 0, ..., |n/\Delta'|$. PLCP construction is divided into three stages: first we compute the values of ℓ_i for selected evenly spaced indices $i, i = j \cdot \Delta'$ and $j = 0, 1, \ldots, |n/\Delta'|$. We use a slow algorithm for computing lengths that takes $O(\Delta')$ extra time for every ℓ_i . During the second stage we compute all remaining values of ℓ_i . We use the method from [2] during Stage 2. The key to a fast implementation is "parallel" computation. We divide all lengths into groups and assign each group of lengths to a *job*. At any time we process a list containing at least $2n/\log^2 n$ jobs. We answer rank queries in batches: when a job J_i must answer a slow rank query on L or \overline{B} , we pause J_i and add the rank query to the corresponding pool of queries. When a pool of queries on L or the pool of queries on \overline{B} contains $n/\log^2 n$ items, we answer the batch of queries in $O(n/\log^2 n)$ time. The third stage starts when the number of jobs becomes smaller than $2n/\log^2 n$. All lengths that were not computed earlier are computed during Stage 3 using the slow algorithm. Stage 2 can be executed in O(n) time because rank queries are answered in O(1) time per query. Since the number of lengths that we compute during the first and the third stages is small, Stage 1 and Stage 3 also take time O(n). A more detailed description follows.

Stage 1. Our algorithm starts by computing ℓ_i for $i = j \cdot \Delta'$ and $j = 0, 1, \ldots, \lfloor n/\Delta' \rfloor$. Let j = 0and $f = j\Delta'$. We already know the rank r_f of $S_f = T[j\Delta'..]$ in B (r_f was computed and recorded when B was constructed). We can also find the starting position f' of the suffix S' of rank $r_f - 1$, S' = T[f'..]. Since f' can be found by employing the function LF at most Δ' times, we can compute f' in $O(\Delta')$ time; see Section A.1³. When f and f' are known, we scan T[f..] and T[f'..] until the

³A faster computation is possible, but we do not need it here.

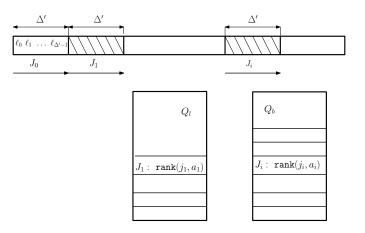


Figure 1: Computing lengths during Stage 2. Groups corresponding to paused jobs are shown shaded by slanted lines. Only selected groups are shown. The *i*-th job J_i is paused because we have to answer a rank query on \overline{B} ; the job J_1 is paused because we have to answer a rank query on L. When Q_l or Q_b contains $n/\log^2 n$ queries, we answer a batch of rank queries contained in Q_l or Q_b .

first symbol $T[f + p_f] \neq T[f' + p_f]$ is found. By definition of ℓ_j , $\ell_0 = p_f - 1$. Suppose that $\ell_{s\Delta'}$ for $s = 0, \ldots, j - 1$ are already computed and we have to compute ℓ_f for $f = j\Delta'$ and some $j \geq 1$. We already know the rank r_f of suffix T[f..]. We find f' such that the suffix T[f'..] is of rank $r_f - 1$ in time $O(\Delta')$. We showed above that $\ell_f \geq \ell_{(j-1)\Delta'} - \Delta'$. Hence the first o_f symbols in T[f..] and T[f'..] are equal, where $o_f = \max(0, \ell_{(j-1)\Delta'} - \Delta')$. We scan $T[f + o_f..]$ and $T[f' + o_f..]$ until the first symbol $T[f + o_f + p_f] \neq T[f' + o_f + p_f]$ is found. By definition, $\ell_f = o_f + p_f$. Hence we compute ℓ_f in $O(\Delta' + p_f)$ time for $f = j\Delta'$ and $j = 1, \ldots, \lfloor n/\Delta' \rfloor$. It can be shown that $\sum_f p_f = O(n)$. Hence the total time needed to compute all selected ℓ_f is $O((n/\Delta')\Delta' + \sum_f p_f) = O(n)$. For every $f = j\Delta'$ we also compute the interval of $T[j\Delta'...j\Delta' + \ell_f]$ in B and the interval of $\overline{T[j\Delta'...j\Delta' + \ell_f]}$ in \overline{B} . We show in Section A.6 that all needed intervals can be computed in O(n) time.

Stage 2. We divide ℓ_i into groups of size $\Delta' - 1$ and compute the values of ℓ_k in every group using a *job*. The *i*-th group contains lengths ℓ_{k+1} , ℓ_{k+2} , ..., $\ell_{k+\Delta'-1}$ for $k = i\Delta'$ and i = 0, 1, ... All ℓ_k in the *i*-th group will be computed by the *i*-th *job* J_i . Every J_i is either active or paused. Thus originally we start with a list of n/Δ' jobs and all of them are active. All active jobs are executed at the same time. That is, we scan the list of active jobs, spend O(1) time on every active job, and then move on to the next job. When a job must answer a rank query, we pause it and insert the query into a query list. There are two query lists: Q_l contain rank queries on sequence L and Q_b contains rank queries on \overline{B} . When Q_l or Q_b contains $n/\log^2 n$ queries, we answer all queries in Q_l (resp. in Q_b). The batch of queries is answered using Theorem 2, so that every query is answered in O(1) time. Answers to queries are returned to jobs, corresponding jobs are re-activated, and we continue scanning the list of active jobs. When all ℓ_k for $i\Delta' \leq k < (i+1)\Delta'$ are computed, the *i*-th job is finished; we remove this job from the pool of jobs and decrement by 1 the number of jobs. See Fig. 1.

Every job J_i computes $\ell_{k+1}, \ell_{k+2}, \ldots, \ell_{k+\Delta'-1}$ for $k = i\Delta'$ using the algorithm of Belazzougui [2]. When the interval of $T[i + \ell_k..]$ in B and the interval of $\overline{T[i + \ell_k..]}$ in \overline{B} are known, we compute ℓ_{k+1} . The procedure for computing ℓ_{k+1} must execute one operation contractleft and ℓ_{k+1} – $\ell_k + 1$ operations extendright. Operations contractleft and extendright are implemented as described above. We must answer two rank queries on \overline{B} and one rank query on L for every extendright. Ignoring the time for these three rank queries, extendright takes constant time. Rank queries on \overline{B} and L are answered in batches, so that each rank query takes O(1) time. Hence every operation extendright needs O(1) time. The job J_i needs $O(\ell_{i\Delta'+j} - \ell_{i\Delta'} + j)$ time to compute $\ell_{i\Delta'+1}, \ell_{i\Delta'+1}, \ldots, \ell_{i\Delta'+j}$. All J_i are executed in O(n) time.

Stage 3. "Parallel processing" of jobs terminates when the number of jobs in the pool becomes smaller than $2n/\log^2 n$. Since every job computes Δ' values of ℓ_i , there are at most $2n(\log \log \sigma/(\log n \log \sigma)) < 2n/\log n$ unknown values of ℓ_i at this point. We then switch to the method of Stage 1 to compute the values of unknown ℓ_i . All remaining ℓ_i are sorted by i and processed in order of increasing i. For every unknown ℓ_i we compute the rank r of T[i..] in B. For the suffix S' of rank r-1 we find its starting position f' in T, S' = T[f'..]. Then we scan $T[f'+\ell_{i-1}-1..]$ and $T[i+\ell_{i-1}-1..]$ until the first symbol $T[f'+\ell_{i-1}+j-1] \neq T[f+\ell_{i-1}+j-1]$ is found. We set $\ell_i = \ell_{i-1} + j - 2$ and continue with the next unknown ℓ_i . We spend $O(\Delta' + \ell_i)$ additional time for every remaining ℓ_i ; hence the total time needed to compute all ℓ_i is $O(n + (n/\log n)\Delta') = O(n)$.

Every job during Stage 2 uses $O(\log n)$ bits of workspace. The total number of jobs in the job list does not exceed n/Δ' . The total number of queries stored at any time in lists Q_l and Q_b does not exceed $n/\log^2 n$. Hence our algorithm uses $O(n \log \sigma)$ bits of workspace.

Lemma 2 If the BWT of a string T and the suffix tree topology for T are already known, then we can compute the permuted LCP array in O(n) time and $O(n \log \sigma)$ bits.

6 Conclusions

We have shown that the Burrows-Wheeler Transform (BWT), the Compressed Suffix Array (CSA), and the Compressed Suffix Tree (CST) can be built in deterministic O(n) time by an algorithm that requires $O(n \log \sigma)$ bits of working space. Belazzougui independently developed an alternative solution, which also builds within the same time and space the simpler part of our structures, that is, the BWT and the CSA, but not the CST. His solution, that uses different techniques, is described in the updated version of his ArXiV report [3] that extends his conference paper [2].

Our results have many interesting applications. For example, we can now construct an FMindex [14, 15] in O(n) deterministic time using $O(n \log \sigma)$ bits. Previous results need $O(n \log \log \sigma)$ time or rely on randomization [23, 2]. Furthermore Theorem 5 enables us to support the function LF in O(1) time on an FM-index. In Section A.7 we describe a new index based on these ideas.

Another application is that we can now compute the Lempel-Ziv 77 and 78 parsings [29, 46, 47] of a string T[0..n-1] in deterministic linear time using $O(n \log \sigma)$ bits: Köppl and Sadakane [27] recently showed that, if one has a compressed suffix tree on T, then they need only O(n) additional (deterministic) time and $O(z \log n)$ bits to produce the parsing, where z is the resulting number of phrases. Since $z \leq n/\log_{\sigma} n$, the space is $O(n \log \sigma)$ bits. With the suffix tree, they need to compute in constant time any $\Psi(i)$ and to move in constant time from a suffix tree node to its *i*-th child. The former is easily supported as the inverse of the LF function using constant-time select queries on B [19]; the latter is also easily obtained with current topology representations using parentheses [36].

Yet another immediate application of our algorithm are index data structures for dynamic document collections. If we use our compressed index, described in Section A.7, and apply Transformation 2 from [32], then we obtain an index data structure for a dynamic collection of documents that uses $nH_k + o(n\log\sigma) + O(n\frac{\log n}{s})$ bits where H_k is the k-th order entropy and s is

a parameter. This index can count how many times a query pattern P occurs in a collection in $O(|P| \log \log n + \log \log \sigma \log \log n)$ time; every occurrence can be then reported in time O(s). An insertion or a deletion of some document T_u is supported in $O(|T_u| \log^{\varepsilon} n)$ and $O(|T_u| (\log^{\varepsilon} n + s))$ deterministic time respectively.

We believe that our technique can also improve upon some of the recently presented results on bidirectional FM-indices [42, 5] and other scenarios where compressed suffix trees are used [6].

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A.1 Preliminaries

Rank and Select Queries The following two kinds of queries play a crucial role in compressed indexes and other succinct data structures. Consider a sequence B[0..n-1] of symbols over an alphabet of size σ . The rank query rank_a(i, B) counts how many times a occurs among the first i+1 symbols in B, rank_a $(i, B) = |\{j | B[j] = a \text{ and } 0 \le j < i\}|$. The select query select_a(i, B) finds the position in B where a occurs for the *i*-th time, select_a(i, B) = j where j is such that B[j] = aand rank_a(j, B) = i. The third kind of query is the access query, access(i, B), which returns the (i+1)-th symbol in B, B[i]. If insertions and deletions of symbols in B must be supported, then both kinds of queries require $\Omega(\log n / \log \log n)$ time [17]. If the sequence B is static, then we can answer select queries in O(1) time and the cost of rank queries is reduced to $\Theta(\log \frac{\log \sigma}{\log \log n})$ [8].⁴ One important special case of rank queries is the partial rank query, rank_{B[i]}(i, B). Thus a partial rank query asks how many times B[i] occurred in B[0..i]. Unlike general rank queries, partial rank queries can be answered in O(1) time [8]. In Section A.4 we describe a data structure for partial rank queries that can be constructed in O(n) deterministic time. Better results can be achieved in the special case when the alphabet size is $\sigma = \log^{O(1)} n$; in this case we can represent B so that rank, select, and access queries are answered in O(1) time [15].

Suffix Tree and Suffix Array. A suffix tree for a string T[0..n-1] is a compacted tree on the suffixes of T. The suffix array is an array SA[0..n-1] such that SA[i] = j if and only if T[j..] is the (i+1)-th lexicographically smallest suffix of T. All occurrences of a substring p in T correspond to suffixes of T that start with p; these suffixes occupy a contiguous interval in the suffix array SA.

Compressed Suffix Array. A compressed suffix array (CSA) is a compact data structure that provides the same functionality as the suffix array. The main component of CSA is the function Ψ , defined by the equality $SA[\Psi(i+1)] = (SA[i]+1) \mod n$. It is possible to regenerate the suffix array from Ψ . We refer to [33] and references therein for a detailed description of CSA and for trade-offs between space usage and access time.

Burrows-Wheeler Transform and FM-index. The Burrows-Wheeler Transform (BWT) of a string T is obtained by sorting all possible rotations of T and writing the last symbol of every rotation (in sorted order). The BWT is related to the suffix array as follows: $BWT[i] = T[(SA[i]-1) \mod n]$. Hence, we can build the BWT by sorting the suffixes and writing the symbols that precede the suffixes in lexicographical order. This method is used in Section 2.

The FM-index uses the BWT for efficient searching in T. It consists of the following three main components:

- The BWT of T.
- The array $Acc[0..\sigma 1]$ where Acc[i] holds the total number of symbols $a \leq i 1$ in T (or equivalently, the total number of symbols $a \leq i 1$ in B).
- A sampled array SAM_b for a sampling factor b: SAM_b contains values of SA[i] if and only if $SA[i] \mod b = 0$ or SA[i] = n 1.

The search for a substring P of length m is performed backwards: for i = m - 1, m - 2, ..., we identify the interval of p[i..m] in the BWT. Let B denote the BWT of T. Suppose that we know the

⁴If we aim to use $n \log \sigma + o(n \log \sigma)$ bits, then either select or access must cost $\omega(1)$. If, however, $(1 + \epsilon)n \log \sigma$ bits are available, for any constant $\epsilon > 0$, then we can support both queries in O(1) time.

interval $B[i_1..j_1]$ that corresponds to p[i + 1..m - 1]. Then the interval $B[i_2..j_2]$ that corresponds to p[i..m - 1] is computed as $i_2 = \operatorname{rank}_c(i_1 - 1, B) + Acc[c]$ and $j_2 = \operatorname{rank}_c(i_2, B) + Acc[c] - 1$, where c = P[i]. Thus the interval of p is found by answering 2m rank queries. We observe that the interval of p in B is exactly the same as the interval of p in the suffix array SA.

Another important component of an FM-index is the function LF, defined as follows: if SA[j] = i + 1, then SA[LF(j)] = i. LF can be computed by answering rank queries on B. Using LF we can find the starting position of the r-th smallest suffix, SA[r], in O(b) applications of LF, where b is the sampling factor; we refer to [33] for details. It is also possible to compute the function Ψ by using select queries the BWT [28]. Therefore the BWT can be viewed as a variant of the CSA. Using Ψ we can consecutively obtain positions of suffixes T[i..] in the suffix array: Let r_i denote the position of T[i..] in SA. Since T[n - 1..] = is the smallest suffix, $r_0 = \Psi(0)$. For $i \ge 1$, $r_i = \Psi(r_{i-1})$ by definition of Ψ . Hence we can consecutively compute each r_i in O(1) time if we have constant-time select queries on the BWT.

Compressed Suffix Tree. A compressed suffix tree consists of the following components:

- The compressed suffix array of T. We can use the FM-index as an implementation.
- The suffix tree topology. This component can be stored in 4n + o(n) bits [40].
- The permuted LCP array, or PLCP. The longest common prefix array LCP is defined as follows: LCP[r] = j if and only if the longest common prefix between the suffixes of rank r and r-1 is of length j. The permuted LCP array is defined as follows: PLCP[i] = j if and only if the rank of T[i..] is r and LCP[r] = j. A careful implementation of PLCP occupies 2n + o(n) bits [40].

A.2 Monotone List Labelling with Batched Updates

A direct attempt to dynamize the data structure of Section 3 encounters one significant difficulty. An insertion of a new symbol a into a chunk C changes the positions of all the symbols that follow it. Since symbols are stored in pairs (a_j, i) grouped by symbol, even a single insertion into C can lead to a linear number of updates. Thus it appears that we cannot support the batch of updates on C in less than $\Theta(|C|)$ time. In order to overcome this difficulty we employ a monotone labeling method and assign labels to positions of symbols. Every position i in the chunk is assigned an integer label lab(i) satisfying $0 \leq \text{lab}(i) \leq \sigma \cdot n^{O(1)}$ and lab $(i_1) < \text{lab}(i_2)$ if and only if $i_1 < i_2$. Instead of pairs (a, i) the sequence R will contain pairs (a, lab(i)).

When a new element is inserted, we have to change the labels of some other elements in order to maintain the monotonicity of the labeling. Existing labeling schemes [45, 11, 12] require $O(\log^2 n)$ or $O(\log n)$ changes of labels after every insertion. In our case, however, we have to process large batches of insertions. We can also assume that at most $\log n$ batches need to be processed. In our scenario O(1) amortized modifications per insertion can be achieved, as shown below.

In this section we denote by C an ordered set that contains between σ and 2σ elements. Let $x_1 \leq x_2 \leq \ldots \leq x_t$ denote the elements of C. Initially we assign the label $lab(x_i) = i \cdot d$ to the *i*-th smallest element x_i , where d = 4n. We associate an interval $[lab(x_i), lab(x_{i+1}) - 1]$ with x_i . Thus initially the interval of x_i is [id, (i+1)d - 1]. We assume that C also contains a dummy element $x_0 = -\infty$ and $lab(-\infty) = 0$. Thus all labels are non-negative integers bounded by $O(\sigma \cdot n)$.

Suppose that the k-th batch of insertions consists of m new elements $y_1 \le y_2 \le \ldots \le y_m$. Since at most log n batches of insertions must be supported, $1 \le k \le \log n$. We say that an element y_j is

in an interval $I = [lab(x_s), lab(x_e)]$ if $x_s < y_i < x_e$. We denote by new(I) the number of inserted elements in I. The parameter $\rho(I)$ for an interval I is defined as the ratio of old and new elements in $I = [\operatorname{lab}(x_s), \operatorname{lab}(x_e)], \ \rho(I) = \frac{e^{-s+1}}{new(I)}$. We identify the set of non-overlapping intervals I_1, \ldots, I_r such that every new element y_t is in some interval I_j , and $1 \le \rho(I_j) \le 2$ for all $j, 1 \le j \le r$. (This is always possible if $m \leq |C|$; otherwise we simply merge the insertions with C in O(|C|+m) = O(m)time and restart all the labels.) We can find I_1, \ldots, I_r in O(m) time. For every $I_j, 1 \leq j \leq r$, we evenly distribute the labels of old and new elements in the interval $I'_j \subseteq I_j$. Suppose that f new elements y_p, \ldots, y_{p+f-1} are inserted into interval $I_j = [lab(x_s), lab(x_e)]$ so that now there are v = f + (e - s) + 1 elements in this interval. We assign the label $lab(x_s) + d_i \cdot (i - 1)$ to the *i*-th smallest element in I_j where $d_j = \frac{\operatorname{lab}(x_e) - \operatorname{lab}(x_s)}{v-1}$. By our choice of I_j , $f \le e-s+1$ and the number of elements in I_j increased at most by twofold. Hence the minimal distance between two consecutive labels does not decrease by more than a factor of 2 after insertion of new elements into I_j . We inserted f new elements into I_i and changed the labels of at most 2f old elements. Hence the amortized number of labels that we must change after every insertion is O(1). The initial distance between labels is d = 4n and this distance becomes at most two times smaller after every batch of insertions. Hence the distance between consecutive labels is an integer larger than 2 during the first $\log n$ batches.

One remaining problem with our scheme is the large range of the labels. Since labels are integers bounded by 4|C|n, we need $\Theta(\log \sigma + \log n)$ bits per label. To solve this problem, we will split the chunk C into blocks and assign the same label to all the symbols in a block. A label assigned to the symbols in a block will be stored only once. Details are provided in Section A.3.

A.3 Batched Rank Queries and Insertions on a Sequence

In this section we describe a dynamic data structure that supports both batches of rank queries and batches of insertions. First we describe how queries and updates on a chunk C are supported.

The linked list L contains all the symbols of C in the same order as they appear in C. Each node of L stores a block of $\Theta(\log_{\sigma} n)$ symbols, containing at most $(1/4)\log_{\sigma} n$ of them. We will identify list nodes with the blocks they contain; however, the node storing block b also stores the total number of symbols in all preceding blocks and a label lab(b) for the block. Labels are assigned to blocks with the method described in Section A.2. The pointer to (the list node containing) block b will be called p_b ; these pointers use $O(\log \sigma)$ bits.

We also maintain a data structure that can answer rank queries on any block. The data structure for a block supports queries and insertions in O(1) time using a look-up table: Since $\sigma \leq n^{1/4}$ and the block size is $(1/4) \log_{\sigma} n$, we can keep pre-computed answers to all rank queries for all possible blocks in a table $Tbl[0..n^{1/4} - 1][0..n^{1/4} - 1][0..\log_{\sigma} n - 1]$. The entry Tbl[b][a][i] contains the answer to the query rank_a(i, b) on a block b. Tbl contains $O(n^{1/2} \log_{\sigma} n) = o(n)$ entries and can be constructed in o(n) time. Updates can be supported by a similar look-up table or by bit operations on the block b.

We also use sequences R and R', defined in Section 3, but we make the following modifications. For every occurrence C[i] = a of a symbol a in C, the sequence R contains pair (a, p_b) , where p_b is a pointer to the block b of L that contains C[i]. Pairs are sorted by symbol in increasing order, and pairs with the same symbol are sorted by their position in C. Unlike in Section 3, the chunk Ccan be updated and we cannot maintain the exact position i of C[i] for all symbols in C; we only maintain the pointers p_b in the pairs $(a, p_b) \in R$.

Note that we cannot use block pointers for searching in L (or in C). Instead, block labels are

monotonously increasing and $lab(b_1) < lab(b_2)$ if the block b_2 follows b_1 in L. Hence block labels will be used for searching and answering rank queries. Block labels lab(b) use $\Theta(\log n)$ bits of space, so we store them only once with the list nodes b and access them via the pointers p_b .

Groups $H_{a,j}$ are defined as in Section 3; each $H_{a,j}$ contains all the pairs of R that are between two consecutive elements of R'_a for some a. The data structure $D_{a,j}$ that permits searching in $H_{a,j}$ is defined as follows. Suppose that $H_{a,j}$ contains pairs $(a, p_{b_1}), \ldots, (a, p_{b_f})$. We then keep a Succinct SB-tree data structure [20] on $lab(b_1), \ldots, lab(b_f)$. This data structure requires O(log log n)additional bits per label. For any integer q, it can find the largest block label $lab(b_i) < q$ in O(1)time or count the number of blocks b_i such that $lab(b_i) < q$ in O(1) time (because our sets $H_{a,r}$ contain a logarithmic number of elements). The search procedure needs to access one block label, which we read from the corresponding block pointer.

Queries. Suppose that we want to answer queries $\operatorname{rank}_{a_1}(i_1, C)$, $\operatorname{rank}_{a_2}(i_2, C)$, ..., $\operatorname{rank}_{a_t}(i_t, C)$ on a chunk C. We traverse all the blocks of L and find for every i_j the label l_j of the block b_j that contains the i_j -th symbol, $l_j = \operatorname{lab}(b_j)$. We also compute $r_{j,1} = \operatorname{rank}_{a_j}(i'_j, b_j)$ using Tbl, where i'_j is the relative position of the i_j -th symbol in b_j . Since we know the total number of symbols in all the blocks that precede b_j , we can compute i'_j in O(1) time.

We then represent the queries by pairs (a_j, l_j) and sort these pairs stably in increasing order of a_j . Then we traverse the list of query pairs (a_j, l_j) and the sequence R'. For every query (a_j, l_j) we find the rightmost pair $(a_j, p_j) \in R'$ satisfying $lab(p_j) \leq l_j$. Let $r_{j,2}$ denote the rank of (a_j, p_j) in R_{a_j} , i.e., the number of pairs $(a_j, i) \in R$ preceding (a_j, p_j) . We keep this information for every pair in R' using $O(\log \sigma)$ additional bits. Then we use the succinct SB-tree D_{a_j,p_j} , which contains information about the pairs in H_{a_j,p_j} (i.e., the pairs in the group starting with (a_j, p_j)). The structure finds in constant time the largest $lab(b_g) \in D_{a_j,p_j}$ such that $lab(b_g) < l_j$, as well as the number $r_{j,3}$ of pairs from the beginning of H_{a_j,p_j} up to the pair with $label lab(b_g)$. The answer to the *j*-th rank query is then $rank_{a_j}(i_j, C) = r_{j,1} + r_{j,2} + r_{j,3}$.

The total query time is then $O(\sigma/\log_{\sigma} n + t)$.

Insertions. Suppose that symbols a_1, \ldots, a_t are to be inserted at positions i_1, \ldots, i_t , respectively. We traverse the list L and identify the nodes where new symbols must be inserted. We simultaneously update the information about the number of preceding elements, for all nodes. All this is done in time $O(\sigma/\log_{\sigma} n + t)$. We also perform the insertions into the blocks. If, as a result, some block contains more than $(1/4) \log_{\sigma} n$ symbols, we split it into an appropriate number of blocks, so that each block contains $\Theta(\log_{\sigma} n)$ but at most $(1/4) \log_{\sigma} n$ symbols. Nodes for the new blocks are allocated⁵, linked to the list L, and assigned appropriate labels using the method described in Section A.2. After t insertions, we create at most $O(t/\log_{\sigma} n)$ new blocks (in the amortized sense, i.e., if we consider the insertions from the beginning). Each such new block b', coming from splitting an existing block b, requires that we change all the corresponding pointers p_b from the pairs (a_z, p_b) in R (and R'), so that they become $(a_z, p_{b'})$. To find those pairs efficiently, the list node holding b also contains the $O(\log_{\sigma} n)$ pointers to those pairs (using $O(\log \sigma)$ bits each); we can then update the required pointers in O(t) total time.

The new blocks also require creating their labels. Those $O(t/\log_{\sigma} n)$ label insertions also trigger $O(t/\log_{\sigma} n)$ changes of other labels, with the technique of Section A.2. If the label of a block b was changed, we visit all pairs (a_z, p_b) in R that point to b. Each such (a_z, p_b) is kept in some

⁵Constant-time allocation is possible because we use fixed-size nodes, leaving the maximum possible space, $(1/4) \log n$ bits, for the block contents.

group $H_{a_z,k}$ and in some succinct SB-tree $D_{a_z,k}$. We then delete the old label of b from $D_{a_z,k}$ and insert the new modified label. The total number of updates is thus bounded by O(t). While not mntioned in the original paper [20], one can easily perform constant-time insertions and deletions of labels in a succinct SB-tree: The structure is a two-level B-tree of arity $\sqrt{\log n}$ holding encoded Patricia trees on the bits of the keys, and storing at the leaves the positions of the keys in $H_{a,r}$ using $O(\log \log n)$ bits each. To insert or delete a label we follow the usual B-tree procedures. The insertion or deletion of a key in a B-tree node is done in constant time with a precomputed table that, in the same spirit of Tbl, yields the resulting Patricia tree if we delete or insert a certain node; this is possible because internal nodes store only $O(\sqrt{\log n} \log \log n) = o(\log n)$ bits. Similarly, we can delete or insert a key at the leaves of the tree.

Apart from handling the block overflows, we must insert in R the pairs corresponding to the new t symbols we are actually inserting. We perform t rank queries $\operatorname{rank}_{a_1}(i_1, C), \ldots, \operatorname{rank}_{a_t}(i_t, C)$, just as described above, and sort the symbols to insert by those ranks using radix sort. We then traverse R' and identify the groups $H_{a_1,j_1}, \ldots, H_{a_t,j_t}$ where new symbols must be inserted; the counters of preceding pairs for the pairs in R' is easily updated in the way. We allocate the pairs (a_k, p_{b_k}) that will belong to H_{a_i,j_i} and insert the labels $\operatorname{lab}(b_k)$ in the corresponding data structures D_{a_k,j_k} , for all $1 \leq k \leq t$. If some groups H_{a_t,j_t} become larger than permitted, we split them as necessary and insert the corresponding pairs in R'. We can answer the rank queries, traverse R, and update the groups H_{a_k,j_k} all in $O(\sigma/\log_{\sigma} n + t)$ time.

Global Sequence. In addition to chunk data structures, we keep a static bitvector $M_a = 1^{d_1} 0 \dots 1^{d_s}$ for every symbol a; d_i denotes the number of times a occurs in the *i*-th chunk.

Given a global sequence of $m \ge n/\log_{\sigma} n$ queries, $\operatorname{rank}_{a_1}(i_1, B), \ldots, \operatorname{rank}_{a_m}(i_m, B)$ on B, we can assign them to chunks in O(m) time. Then we answer queries on chunks as shown above. If m_j queries are asked on chunk C_j , then these queries are processed in $O(m_j + \sigma/\log_{\sigma} n)$ time. Hence all queries on all chunks are answered in $O(m + n/\log_{\sigma} n) = O(m)$ time. We can answer a query $\operatorname{rank}_{a_k}(i_k, B)$ by answering a rank query on the chunk that contains $B[i_k]$ and O(1) queries on the sequence M_{a_k} [19]. Queries on M_{a_k} are supported in O(1) time because the bitvector is static. Hence the total time to answer m queries on B is O(m).

When a batch of symbols is inserted, we update the corresponding chunks as described above. If some chunk contains more than 4σ symbols, we split it into several chunks of size $\Theta(\sigma)$ using standard techniques. Finally we update the global sequences M_a , both because of the insertions and due to the possible chunk splits. We simply rebuild the bitvectors M_a from scratch; this is easily done in $O(n_a/\log n)$ time, where n_a is the number of bits in M_a ; see e.g. [31]. This adds up to $O(m/\log n)$ time.

Hence the total amortized cost for a batch of $m \ge n/\Delta$ insertions is O(m).

Theorem 4 We can keep a sequence B[0..n-1] over an alphabet of size σ in $O(n \log \sigma)$ bits of space so that a batch of m rank queries can be answered in O(m) time and a batch of m insertions is supported in O(m) amortized time, for $\frac{n}{\log_{\sigma} n} \leq m \leq n$.

A.4 Sequences with Partial Rank Operation

If $\sigma = \log^{O(1)} n$, then we can keep a sequence S in $O(n \log \sigma)$ bits so that select and rank queries (including partial rank queries) are answered in constant time [15]. In the remaining part of this section we will assume that $\sigma \ge \log^3 n$.

Lemma 3 Let $\sigma \leq m \leq n$. We can support partial rank queries on a sequence C[0..m-1] over an alphabet of size σ in time O(1). The data structure needs $O(m \log \log m)$ additional bits and can be constructed in O(m) deterministic time.

Proof: Our method employs the idea of buckets introduced in [4]. Our structure does not use monotone perfect hashing, however. Let I_a denote the set of positions where a symbol a occurs in C, i.e., I_a contains all integers i satisfying C[i] = a. If I_a contains more than $2 \log^2 m$ integers, we divide I_a into buckets $B_{a,s}$ of size $\log^2 m$. Let $p_{a,s}$ denote the longest common prefix of all integers (seen as bit strings) in the bucket $B_{a,s}$ and let $l_{a,s}$ denote the length of $p_{a,s}$. For every element C[i]in the sequence we keep the value of $l_{C[i],t}$ where $B_{C[i],t}$ is the bucket containing i. If $I_{C[i]}$ was not divided into buckets, we assume $l_{C[i],t} = null$, a dummy value. We will show below how the index t of $B_{C[i],t}$ can be identified if $l_{C[i],t}$ is known. For every symbol C[i] we also keep the rank r of iin its bucket $B_{C[i],t}$. That is, for every C[i] we store the value of r such that i is the r-th smallest element in its bucket $B_{C[i],t}$. Both $l_{C[i],t}$ and r can be stored in $O(\log \log m)$ bits. The partial rank of C[i] in C can be computed from t and r, $\operatorname{rank}_{C[i]}(i, C) = t \log^2 m + r$.

It remains to describe how the index t of the bucket containing C[i] can be found. Our method uses o(m) additional bits. First we observe that $p_{a,i} \neq p_{a,j}$ for any fixed a and $i \neq j$; see [4] for a proof. Let T_w denote the full binary trie on the interval [0..m-1]. Nodes of T_w correspond to all possible bit prefixes of integers $0, \ldots, m-1$. We say that a bucket $B_{a,j}$ is assigned to a node $u \in T_w$ if $p_{a,j}$ corresponds to the node u. Thus many different buckets can be assigned to the same node u. But for any symbol a at most one bucket $B_{a,k}$ is assigned to u. If a bucket is assigned to a node u, then there are at least $\log^2 m$ leaves below u. Hence buckets can be assigned to nodes of height at least $2 \log \log m$; such nodes will be further called bucket nodes. We store all buckets assigned to bucket nodes of T_w using the structure described below.

We order the nodes u level-by-level starting at the top of the tree. Let m_j denote the number of buckets assigned to u_j . The data structure G_j contains all symbols a such that some bucket B_{a,k_a} is assigned to u_j . For every symbol a in G_j we can find in O(1) time the index k_a of the bucket B_{a,k_a} that is assigned to u_j . We implement G_j as deterministic dictionaries of Hagerup et al. [22]. G_j uses $O(m_j \log \sigma)$ bits and can be constructed in $O(m_j \log \sigma)$ time. We store G_j only for bucket nodes u_j such that $m_j > 0$. We also keep an array $W[1..\frac{m}{\log^2 m}]$ whose entries correspond to bucket nodes of T_w : W[j] contains a pointer to G_j or null if G_j does not exist.

Using W and G_j we can answer a partial rank query $\operatorname{rank}_{C[i]}(i, C)$. Let C[i] = a. Although the bucket $B_{a,t}$ containing *i* is not known, we know the length $l_{a,t}$ of the prefix $p_{a,t}$. Hence $p_{a,t}$ can be computed by extracting the first $l_{a,t}$ bits of *i*. We can then find the index *j* of the node u_j that corresponds to $p_{a,t}$, $j = (2^{l_{a,t}} - 1) + p_{a,t}$. We lookup the address of the data structure G_j in W[j]. Finally the index *t* of the bucket $B_{a,t}$ is computed as $t = G_j[a]$.

A data structure G_j consumes $O(m_j \log m)$ bits. Since $\sum_j m_j \leq \frac{m}{\log^2 m}$, all G_j use $O(m/\log m)$ bits of space. The array W also uses $O(m/\log m)$ bits. Hence our data structure uses $O(\log \log m)$ additional bits per symbol.

Theorem 5 We can support partial rank queries on a sequence B using $O(n \log \log \sigma)$ additional bits. The underlying data structure can be constructed in O(n) deterministic time.

Proof: We divide the sequence B into chunks of size σ (except for the last chunk that contains $n - (\lfloor n/\sigma \rfloor \sigma)$ symbols). Global sequences M_a are defined in the same way as in Section 3. A partial rank query on B can be answered by a partial rank query on a chunk and two queries on M_a . \Box

A.5 Reporting All Symbols in a Range

We prove the following lemma in this section.

Lemma 4 Given a sequence B[0..n-1] over an alphabet σ , we can build in O(n) time a data structure that uses $O(n \log \log \sigma)$ additional bits and answers the following queries: for any range [i..j], report occ distinct symbols that occur in B[i..j] in O(occ) time, and for every reported symbol a, give its frequency in B[i..j] and its frequency in B[0..i-1].

The proof is the same as that of Lemma 3 in [2], but we use the result of Theorem 5 to answer partial rank queries. This allows us to construct the data structure in O(n) deterministic time (while the data structure in [2] achieves the same query time, but the construction algorithm requires randomization). For completeness we sketch the proof below.

Augmenting B with O(n) additional bits, we can report all distinct symbols occurring in B[i..j]in $O(\operatorname{occ})$ time using the idea originally introduced by Sadakane [41]. For every reported symbol we can find in O(1) time its leftmost and its rightmost occurrences in B[i..j]. Suppose i_a and j_a are the leftmost and rightmost occurrences of a in B[i..j]. Then the frequencies of a in B[i..j] and B[0..i-1] can be computed as $\operatorname{rank}_a(j_a, B) - \operatorname{rank}_a(i_a, B) + 1$ and $\operatorname{rank}_a(i_a, B) - 1$ respectively. Since $\operatorname{rank}_a(i_a, B)$ and $\operatorname{rank}_a(j_a, B)$ are partial rank queries, they are answered in O(1) time. The data structure that reports the leftmost and the rightmost occurrences can be constructed in O(n) time. Details and references can be found in [9]. Partial rank queries are answered by the data structure of Theorem 5. Hence the data structure of Lemma 4 can be built in O(n) deterministic time. We can also use the data structure of Lemma 5 to determine whether the range B[i..j] contains only one distinct symbol in O(1) time by using the following observation. If B[i..j] contains only one symbol, then B[i] = B[j] and $\operatorname{rank}_{B[i]}(j, B) - \operatorname{rank}_{B[i]}(i, B) = j - i + 1$. Hence we can find out whether B[i..j] contains exactly one symbol in O(1) time by answering two partial rank queries. This observation will be helpful in Section 5.

A.6 Computing the Intervals

The algorithm for constructing PLCP, described in Section 5, requires that we compute the intervals of $T[j\Delta'..j\Delta' + \ell_i]$ and $\overline{T[j\Delta'..j\Delta' + \ell_i]}$ for $i = j\Delta'$ and $j = 0, 1, \ldots, n/\Delta'$. We will show in this section how all necessary intervals can be computed in linear time when ℓ_i for $i = j\Delta'$ are known. Our algorithm uses the suffix tree topology. We construct some additional data structures and pointers for selected nodes of the suffix tree \mathcal{T} . First, we will describe auxiliary data structures on \mathcal{T} . Then we show how these structures can be used to find all needed intervals in linear time.

Marking Nodes in a Tree. We use the marking scheme described in [34]. Let $d = \log n$. A node u of \mathcal{T} is *heavy* if it has at least d leaf descendants and *light* otherwise. We say that a heavy node u is a *special* or marked node if u has at least two heavy children. If a non-special heavy node u has more than d children and among them is one heavy child, then we keep the index of the heavy child in u.

We keep all children of a node u in the data structure F_u , so that the child of u that is labeled by a symbol a can be found efficiently. If u has at most d + 1 children, then F_u is implemented as a fusion tree [18]; we can find the child of u labeled by any symbol a in O(1) time. If u has more than d + 1 children, then F_u is implemented as the van Emde Boas data structure and we can find the child labeled by a in $O(\log \log \sigma)$ time. If the node u is special, we keep labels of its heavy children in the data structure D_u . D_u is implemented as a dictionary data structure [22] so that we can find any heavy child of a special node in O(1) time. We will say that a node u is difficult if u is light but the parent of u is heavy. We can quickly navigate from a node $u \in \mathcal{T}$ to its child u_i unless the node u_i is difficult.

Proposition 2 We can find the child u_i of u that is labeled with a symbol a in O(1) time unless the node u_i is difficult. If u_i is difficult, we can find u_i in $O(\log \log \sigma)$ time.

Proof: Suppose that u_i is heavy. If u is special, we can find u_i in O(1) time using D_u . If u is not special and it has at most d + 1 children, then we find u_i in O(1) time using F_u . If u is not special and it has more than d + 1 children, then u_i is the only heavy child of u and its index i is stored with the node u. Suppose that u_i is light and u is also light. Then u has at most d children and we can find u_i in O(1) time using F_u . If u is heavy and u_i is light, then u_i is a difficult node. In this case we can find the index i of u_i in $O(\log \log \sigma)$ time using F_u .

Proposition 3 Any path from a node u to its descendant v contains at most one difficult node.

Proof: Suppose that a node u is a heavy node and its descendant v is a light node. Let u' denote the first light node on the path from u to v. Then all descendants of u' are light nodes and u' is the only difficult node on the path from u to v. If u is light or v is heavy, then there are apparently no difficult nodes between u and v.

Weiner Links. A Weiner link (or w-link) wlink(v, c) connects a node v of the suffix tree \mathcal{T} labeled by the path p to the node u, such that u is the locus of cp. If wlink(v, c) = u we will say that u is the target node and v is the source of wlink(v,c) and c is the label of wlink(v,c). If the target node u is labeled by cp, we say that the w-link is explicit. If u is labeled by some path cp', such that cp is a proper prefix of cp', then the Weiner link is implicit. We classify Weiner links using the same technique that was applied to nodes of the suffix tree above. Weiner links that share the same source node are called sibling links. A Weiner link from v to u is *heavy* if the node u has at least d leaf descendants and light otherwise. A node v is w-special iff there are at least two heavy w-links connecting v and some other nodes. For every special node v the dictionary D'_v contains the labels c of all heavy w-links wlink(v,c). For every c such that wlink(v,c) is heavy, we also keep the target node u = wlink(v, c). D'_v is implemented as in [22] so that queries are answered in O(1) time. Suppose that v is the source node of at least d+1 w-links, but u = wlink(v,c) is the only heavy link that starts at v. In this case we say that wlink(v, c) is unique and we store the index of u and the symbol c in v. Summing up, we store only heavy w-links that start in a w-special node or unique w-links. All other w-links are not stored explicitly; if they are needed, we compute them using additional data structures that will be described below.

Let B denote the BWT of T. We split B into intervals G_j of size $4d^2$. For every G_j we keep the dictionary A_j of symbols that occur in G_j . For each symbol a that occurs in G_j , the data structure $G_{j,a}$ contains all positions of a in G_j . Using A_j , we can find out whether a symbol a occurs in G_j . Using $G_{j,a}$, we can find for any position i the smallest $i' \geq i$ such that B[i'] = a and B[i'] is in G_j (or the largest $i'' \leq i$ such that B[i''] = a and B[i''] is in G_j). We implement both A_j and $G_{j,a}$ as fusion trees [18] so that queries are answered in O(1) time. Data structures A_j and $G_{j,a}$ for a fixed j need $O(d^2 \log \sigma)$ bits. We also keep (1) the data structure from [19] that supports select queries on B in O(1) time and rank queries on B in $O(\log \log \sigma)$ time and (2) the data structure from Theorem 5 that supports partial rank queries in O(1) time. All additional data structures on the sequence B need $O(n \log \sigma)$ bits.

Proposition 4 The total number of heavy w-links that start in w-special nodes is O(n/d).

Proof: Suppose that u is a w-special node and let p be the label of u. Let c_1, \ldots, c_s denote the labels of heavy w-links with source node u. This means that each c_1p, c_2p, \ldots, c_sp occurs at least d times in T. Consider the suffix tree $\overline{\mathcal{T}}$ of the reverse text \overline{T} . $\overline{\mathcal{T}}$ contains the node \overline{u} that is labeled with \overline{p} . The node \overline{u} has (at least) s children $\overline{u}_1, \ldots, \overline{u}_s$. The edge connecting \overline{u} and \overline{u}_i is a string that starts with c_i . In other words each \overline{u}_i is the locus of $\overline{p}c_i$. Since c_ip occurs at least d times in T, $\overline{p}c_i$ occurs at least d times in \overline{T} . Hence each \overline{u}_i has at least d descendants. Thus every w-special node in \mathcal{T} correspond to a special node in $\overline{\mathcal{T}}$ and every heavy w-link outgoing from a w-special node corresponds to some heavy child of a special node in $\overline{\mathcal{T}}$. Since the number of heavy children of special nodes in a suffix tree is O(n/d), the number of heavy w-links starting in a w-special node is also O(n/d).

Proposition 5 The total number of unique w-links is O(n/d).

Proof: A Weiner link wlink(v, a) is unique only if wlink(v, a) is heavy, all other w-links outgoing from v are light, and there are at least d light outgoing w-links from v. Hence there are at least d w-links for every explicitly stored target node of a unique Weiner link.

We say that wlink(v, a) is difficult if its target node u = wlink(v, a) is light and its source node v is heavy.

Proposition 6 We can compute u = wlink(v, a) of u in O(1) time unless wlink(v, a) is difficult. If the wlink(v, a) is difficult, we can compute u = wlink(v, a) in $O(\log \log \sigma)$ time.

Proof: Suppose that u is heavy. If v is w-special, we can find u in O(1) time using D_u . If v is not w-special and it has at most d + 1 w-children, then we find u_i in O(1) time using data structures on B. Let $[l_v, r_v]$ denote the suffix range of v. The suffix range of u is $[l_u, r_u]$ where $l_u = Acc[a] + \operatorname{rank}_a(l_v - 1, B) + 1$ and $r_u = Acc[a] + \operatorname{rank}_a(r_v, B)$. We can find $\operatorname{rank}_a(r_v, B)$ as follows. Since v has at most d light w-children, the rightmost occurrence of a in $B[l_v, r_v]$ is within the distance d^2 from r_v . Hence we can find the rightmost $i_a \leq r_v$ such that $B[i_a] = a$ by searching in the interval G_j that contains r_v or the preceding interval G_{j-1} . When i_a is found, $\operatorname{rank}_a(r_v, B) = \operatorname{rank}_a(i_a, B)$ can be computed in O(1) time because partial rank queries on B are supported in time O(1). We can compute $\operatorname{rank}_a(l_v - 1, B)$ in the same way. When rank queries are answered, we can find l_u and r_u in constant time. Then we can identify the node u by computing the lowest common ancestor of l_u -th and r_u -th leaves in \mathcal{T} .

If v is not special and it has more than d + 1 outgoing w-links, then u is the only heavy target node of a w-link starting at v; hence, its index i is stored in the node v. Suppose that u is light and v is also light. Then the suffix range $[l_v, r_v]$ of v has length at most d. $B[l_v, r_v]$ intersects at most two intervals G_j . Hence we can find rank_a $(l_v - 1, B)$ and rank_a (r_v, B) in constant time. Then we can find the range $[l_u, r_u]$ of the node u and identify u in time O(1) as described above. If v is heavy and u is light, then wlink(v, a) is a difficult w-link. In this case we need $O(\log \log \sigma)$ time to compute rank_a $(l_v - 1, B)$ and rank_a (r_v, B) . Then we find the range $[l_u, r_u]$ and the node u is found as described above.

Proposition 7 Any sequence of nodes u_1, \ldots, u_t where $u_i = wlink(u_{i-1}, a_{i-1})$ for some symbol a_{i-1} contains at most one difficult w-link.

Proof: Let π denote the path of w-links that contains nodes u_1, \ldots, u_t . Suppose that a node u_1 is a heavy node and u_t is a light node. Let u_l denote the first light node on the path π . Then all nodes on the path from u_l to u_t are light nodes and wlink (u_{l-1}, a_{l-1}) is the only difficult w-link on the path from u_1 to u_t . If u_1 is light or u_t is heavy, then all nodes on π are light nodes (resp. all nodes on π are heavy nodes). In this case there are apparently no difficult w-links between u_1 and u_t .

Pre-processing. Now we show how we can construct above described auxiliary data structures in linear time. We start by generating the suffix tree topology and creating data structures F_u and D_u for all nodes u. For every node u in the suffix tree we create the list of its children u_i and their labels in O(n) time. For every tree node u we can find the number of its leaf descendants using standard operations on the suffix tree topology. Hence, we can determine whether u is a heavy or a light node and whether u is a special node. When this information is available, we generate the data structures F_u and D_u .

We can create data structures necessary for navigating along w-links in a similar way. We visit all nodes u of \mathcal{T} . Let l_u and r_u denote the indexes of leftmost and rightmost leaves in the subtree of u. Let B denote the BWT of T. Using the method of Lemma 4, we can generate the list of distinct symbols in $B[l_u...r_u]$ and count how many times every symbol occurred in $B[l_u...r_u]$ in O(1)time per symbol. If a symbol a occurred more than d times, then wlink(u, a) is heavy. Using this information, we can identify w-special nodes and create data structures D'_u . Using the method of [38], we can construct D'_u in $O(n_u \log \log n_u)$ time. By Lemma 4 the total number of target nodes in all D'_u is O(n/d); hence we can construct all D'_u in o(n) time. We can also find all nodes u with a unique w-link. All dictionaries D'_u and all unique w-links need $O((n/d) \log n) = O(n)$ bits of space.

Supporting a Sequence of extendright Operations.

Lemma 5 If we know the suffix interval of a right-maximal factor T[i..i + j] in \underline{B} and the suffix interval of $\overline{T[i..i + j]}$ in \overline{B} , the we can find the intervals of T[i..i + j + t] and $\overline{T[i..i + j + t]}$ in $O(t + \log \log \sigma)$ time.

Proof: Let \mathcal{T} and $\overline{\mathcal{T}}$ denote the suffix tree for the text T and let $\overline{\mathcal{T}}$ denote the suffix tree of the reverse text T. We keep the data structure for navigating the suffix tree \mathcal{T} , described in Proposition 2 and the data structure for computing Weiner links described in Proposition 6. We also keep the same data structures for $\overline{\mathcal{T}}$. Let $[\ell_{0,s}, \ell_{0,e}]$ denote the suffix interval of T[i..i+j]; let $[\ell'_{0,s}, \ell'_{0,e}]$ denote the suffix interval of $\overline{T[i..i+j]}$. We navigate down the tree following the symbols $T[i+j+1], \ldots$, T[i+j+t]. Let a = T[i+j+k] for some k such that $1 \le k \le t$ and suppose that the suffix interval $[\ell_{k-1,s},\ell_{k-1,e}]$ of T[i..i+j+k-1] and the suffix interval $[\ell'_{k-1,s},\ell'_{k-1,e}]$ of $\overline{T[i..i+j+k-1]}$ are already known. First, we check whether our current location is a node of \mathcal{T} . If $\overline{B}[\ell'_{k-1,s}, \ell'_{k-1,e}]$ contains only one symbol T[i+j+k], then the range of T[i..i+j+k] is identical with the range of T[i..i+j+k-1]. We can calculate the range of $\overline{T[i..i+j+k]}$ in a standard way by answering two rank queries on \overline{B} and O(1) arithmetic operations; see Section A.1. Since $\overline{B}[\ell'_{k-1,s}, \ell'_{k-1,e}]$ contains only one symbol, rank queries that we need to answer are partial rank queries. Hence we can find the range of $\overline{T[i..i+j+k]}$ in time O(1). If $\overline{B}[\ell'_{k-1,s}, \ell'_{k-1,e}]$ contains more than one symbol, then there is a node $u \in \mathcal{T}$ that is labeled with T[i..i+j+k-1]; $u = lca(\ell_{k-1,s}, \ell_{k-1,e})$ where lca(f,g) denotes the lowest common ancestor of the f-th and the g-th leaves. We find the child u' of the node u in \mathcal{T} that is labeled with a = T[i + j + k]. We also compute the Weiner link $\overline{u'} = \texttt{wlink}(\overline{u}, a)$ for a node $\overline{u'} = lca(\ell'_{k-1,s}, \ell'_{k-1,e})$ in $\overline{\mathcal{T}}$. Then $\ell'_{k,s} = \texttt{leftmost_leaf}(\overline{u'})$ and $\ell'_{k,e} = \texttt{rightmost_leaf}(\overline{u'})$. We need to visit at most t nodes of \mathcal{T} and at most t nodes of $\overline{\mathcal{T}}$ in order to find the desired interval. By Proposition 2 and Proposition 3, the total time needed to move down in \mathcal{T} is $O(t + \log \log \sigma)$. By Proposition 6 and Proposition 7, the total time to compute all necessary w-links in $\overline{\mathcal{T}}$ is also $O(t + \log \log \sigma)$.

Finding the Intervals. The algorithm for computing PLCP, described in Section 5, assumes that we know the intervals of $T[j\Delta'..j\Delta'+\ell_i]$ and $\overline{T[j\Delta'..j\Delta'+\ell_i]}$ for $i = j\Delta'$ and $j = 0, 1, \ldots, n/\Delta'$. These values can be found as follows. We start by computing the intervals of $T[0..\ell_0]$ and $\overline{T[0..\ell_0]}$. Suppose that the intervals of $T[j\Delta'..j\Delta'+\ell_i]$ and $\overline{T[j\Delta'..j\Delta'+\ell_i]}$ are known. We can compute $\ell_{(j+1)\Delta'}$ as shown in Section 5. We find the intervals of $T[(j+1)\Delta'..j\Delta'+\ell_i]$ and $\overline{T[(j+1)\Delta'..j\Delta'+\ell_i]}$ in time $O(\Delta')$ by executing Δ' operations contractleft. Each operation contractleft takes constant time. Then we calculate the intervals of $T[(j+1)\Delta'..(j+1)\Delta'+\ell_{i+1}]$ and $\overline{T[(j+1)\Delta'..(j+1)\Delta'+\ell_{i+1}]}$ in $O(\log \log \sigma + (\ell_{i+1} - \ell_i + \Delta'))$ time using Lemma 5. We know from Section 5 that $\sum (\ell_{i+1} - \ell_i) =$ O(n). Hence we compute all necessary intervals in time $O(n + (n/\Delta') \log \log \sigma) = O(n)$.

A.7 Compressed Index

In this section we show how our algorithms can be used to construct a compact index in deterministic linear time. We prove the following result.

Theorem 6 We can construct an index for a text T[0..n-1] over an alphabet of size σ in O(n)deterministic time using $O(n \log \sigma)$ bits of working space. This index occupies $nH_k + o(n \log \sigma) + O(n \frac{\log n}{d})$ bits of space for a parameter d > 0. All occurrences of a query substring P can be counted in $O(|P| + \log \log \sigma)$ time; all occ occurrences of P can be reported in $O(|P| + \log \log \sigma + \operatorname{occ} \cdot d)$ time. An arbitrary substring P of T can be extracted in O(|P| + d) time.

An uncompressed index by Fischer and Gawrychowski [16] also supports counting queries in $O(|P| + \log \log \sigma)$ time; however their data structure uses $\Theta(n \log n)$ bits. We refer to [7] for the latest results on compressed indexes.

Interval Rank Queries. We start by showing how a compressed data structure that supports select queries can be extended to support a new kind of queries that we dub *small interval rank queries*. An interval rank query $\operatorname{rank}_a(i, j, B)$ asks for $\operatorname{rank}_a(i', B)$ and $\operatorname{rank}_a(j', B)$, where i' and j' are the leftmost and rightmost occurrences of the symbol a in B[i..j]; if a does not occur in B[i..j], we return *null*. An interval query $\operatorname{rank}_a(i, j, B)$ is a small interval query if $j - i \leq 2\log^2 \sigma$. Our compressed index relies on the following result.

Lemma 6 Suppose that we are given a data structure that supports access queries on a sequence C[0..m] in time t_{select} . Then, using $O(m \log \log \sigma)$ additional bits, we can support small interval rank queries on C in $O(t_{select})$ time.

Proof: We split C into groups G_i so that every group contains $\log^2 \sigma$ consecutive symbols of S, $G_i = C[i \log^2 \sigma .. (i + 1) \log^2 \sigma - 1]$. Let A_i denote the set of symbols that occur in G_i . We would need $\log \sigma$ bits per symbol to store A_i . Therefore we keep only a dictionary A'_i implemented as a succinct SB-tree [20]. A succinct SB-tree needs $O(\log \log m)$ bits per symbol; using SB-tree, we can determine whether a query symbol a is in A_i in constant time if we can access elements of A_i . We can identify every $a \in A_i$ by its leftmost position in G_i . Since G_i consists of $\log^2 \sigma$ consecutive symbols, a position within G_i can be specified using $O(\log \log \sigma)$ bits. Hence we can access any symbol of A_i in O(1) time. For each $a \in A_i$ we also keep a data structure $I_{a,i}$ that stores all positions where a occurs in G_i . Positions are stored as differences with the left border of G_i : if C[j] = a, we store the difference $j - i \log^2 \sigma$. Hence elements of $I_{a,i}$ can be stored in $O(\log \log \sigma)$ bits per symbol. $I_{a,i}$ is also implemented as an SB-tree.

Using data structures A'_i and $I_{a,i}$, we can answer small interval rank queries. Consider a group $G_t = C[t \log^2 \sigma ...(t+1) \log^2 \sigma - 1]$, an index *i* such that $t \log^2 \sigma \le i \le (t+1) \log^2 \sigma$, and a symbol *a*. We can find the largest $j \le i$ such that C[j] = a and $C[j] \in G_t$: first we look for the symbol *a* in A'_t ; if $a \in A'_t$, we find the predecessor of *j* in $I_{a,t}$. An interval C[i...j] of size $d \le \log^2 \sigma$ intersects at most two groups G_t and G_{t-1} . We can find the rightmost occurrence of a symbol *a* in [i, j] as follows. First we look for the rightmost occurrence $j' \le j$ of *a* in G_t ; if *a* does not occur in $C[t \log^2 \sigma ...j]$, we look for the rightmost occurrence $j' \le t \log^2 \sigma - 1$ of *a* in G_{t-1} . We can find the leftmost occurrence i' of *a* in C[i...j] using a symmetric procedure. When i' and j' are found, we can compute rank_a(i', C) and rank_a(j', C) in O(1) time by answering partial rank queries. Using the result of Theorem 5 we can support partial rank queries in O(1) time and $O(m \log \log \sigma)$ bits.

Our data structure takes $O(m \log \log m)$ additional bits: Dictionaries A'_i need $O(\log \log m)$ bits per symbol. Data structures $I_{a,t}$ and the structure for partial rank queries need $O(m \log \log \sigma)$ bits. We can reduce the space usage from $O(m \log \log m)$ to $O(m \log \log \sigma)$ using the same method as in Theorem 5.

Compressed Index. We mark nodes of the suffix tree \mathcal{T} using the method of Section A.6, but we set $d = \log \sigma$. Nodes of \mathcal{T} are classified into heavy, light, and special as defined in Section A.6. For every special node u, we construct a dictionary data structure D_u that contains the labels of all heavy children of u. If there is child u_j of u, such that the first symbol on the edge from to uto u_j is a_j , then we keep a in D_u . For every $a_j \in D_u$ we store the index j of the child u_j . If a heavy node u has only one heavy child u_j and more than d light children, then we also store data structure D_u for such a node u. If a heavy node has less d children and one heavy child, then we keep the index of the heavy child using $O(\log d) = O(\log \log \sigma)$ bits.

The second component of our index is the Burrows-Wheeler Transform \overline{B} of the reverse text \overline{T} . We keep the data structure that supports partial rank, select, and access queries on \overline{B} . Using e.g., the result from [1], we can support access queries in O(1) time while rank and select queries are answered in $O(\log \log \sigma)$ time. Moreover we construct a data structure, described in Lemma 6, that supports rank queries on a small interval in O(1) time. We also keep the data structure of Lemma 4 on \overline{B} ; using this data structure, we can find in O(1) time whether an arbitrary interval $\overline{B}[l..r]$ contains exactly one symbol. Finally we explicitly store answers to selected rank queries. Let $\overline{B}[l_u..r_u]$ denote the range of \overline{P}_u , where P_u is the string that corresponds to a node u and \overline{P}_u is the reverse of P_u . For all data structures D_u and for every symbol $a \in D_u$ we store the values of rank_a($l_u - 1, \overline{B}$) and rank_a(r_u, \overline{B}).

We will show later in this section that each rank value can be stored in $O(\log \sigma)$ bits. Thus D_u needs $O(\log \sigma)$ bits per element. The total number of elements in all D_u is equal to the number of special nodes plus the number of heavy nodes with one heavy child and at least d light children. Hence all D_u contain O(n/d) symbols and use $O((n/d) \log \sigma) = O(n)$ bits of space. Indexes of heavy children for nodes with only one heavy child and at most d light children can be kept in $O(\log \log \sigma)$ bits. Data structure that supports select, rank, and access queries on \overline{B} uses $nH_k(T) + o(n\log\sigma)$ bits. Auxiliary data structures on \overline{B} need $O(n) + O(n\log \log \sigma)$ bits. Finally we need $O(n\frac{\log n}{d})$ bits to retrieve the position of a suffix in \overline{T} in O(d) time. Hence the space usage of our data structure is $nH_k(T) + o(n\log\sigma) + O(n) + O(n\frac{\log n}{d})$.

Queries. Given a query string P, we will find in time $O(|P| + \log \log \sigma)$ the range of the reversed string \overline{P} in \overline{B} . We will show below how to find the range of $\overline{P[0..i]}$ if the range of $\overline{P[0..i-1]}$ is known. Let $[l_j..r_j]$ denote the range of $\overline{P[0..j]}$, i.e., $\overline{P[0..j]}$ is the longest common prefix of all suffixes in $\overline{B}[l_j..r_j]$. We can compute l_j and r_j from l_{j-1} and r_{j-1} as $l_j = Acc[a] + \operatorname{rank}_a(l_{j-1} - 1, \overline{B}) + 1$ and $r_j = Acc[a] + \operatorname{rank}_a(r_{j-1}, \overline{B})$ for a = P[j] and $j = 0, \ldots, |P|$. Here Acc[f] is the accumulated frequency of the first f - 1 symbols. Using our auxiliary data structures on \overline{B} and additional information stored in nodes of the suffix tree \mathcal{T} , we can answer necessary rank queries in constant time (with one exception). At the same time we traverse a path in the suffix tree \mathcal{T} until the locus of P is found or a light node is reached. Additional information stored in selected tree nodes will help us answer rank queries in constant time. A more detailed description is given below.

Our procedure starts at the root node of \mathcal{T} and we set $l_{-1} = 0, r_{-1} = n - 1$, and i = 0. We compute the ranges $\overline{B}[l_i..r_i]$ that correspond to $\overline{P[0..i]}$ for $i = 0, \ldots, |P|$. Simultaneously we move down in the suffix tree until we reach a light node. Let u denote the last visited node of \mathcal{T} and let a = P[i]. We denote by u_a the next node that we must visit in the suffix tree, i.e., u_a is the locus of P[0..i]. We can compute l_i and r_i in O(1) time if $\operatorname{rank}_a(r_{i-1}, \overline{B})$ and $\operatorname{rank}_a(l_{i-1} - 1, \overline{B})$ are known. We will show below that these queries can be answered in constant time because either (a) the answers to rank queries are explicitly stored in D_u or (b) the rank query that must be answered is a small interval rank query. The only exception is the situation when we move from a heavy node to a light node in the suffix tree; in this situation the rank query takes $O(\log \log \sigma)$ time. For ease of description we distinguish between the following four cases.

(i) Node u is a heavy node and $a \in D_u$. In this case we identify the heavy child u_j of u that is labeled with a. We can also find l_i and r_i in time O(1) because $\operatorname{rank}_a(l_{i-1}, \overline{B})$ and $\operatorname{rank}_a(r_{i-1}, \overline{B})$ are stored in D_u .

(ii) Node u is a heavy node and $a \notin D_u$ or we do not keep the dictionary D_u for the node u. In this case u has at most one heavy child and at most d light children. If u_a is a heavy node (case iia), then the leftmost occurrence of a in $\overline{B}[l_{i-1}..r_{i-1}]$ is within d^2 symbols of l_{i-1} and the rightmost occurrence of a in $\overline{B}[l_{i-1}..r_{i-1}]$ is within d^2 symbols of r_{i-1} . Hence we can find l_i and r_i by answering small interval rank queries rank_a $(l_{i-1}, l_{i-1}+d^2)$ and rank_a $(r_{i-1}-d^2, r_{i-1})$ respectively. If u_a is a light node (case iib), we answer two standard rank queries on \overline{B} in order to compute l_i and r_i .

(iii) If u is a light node, then P[0..i-1] occurs at most d times. Hence $\overline{P[0..i-1]}$ also occurs at most d times and $r_{i-1} - l_{i-1} \leq d$. Therefore we can compute r_i and l_i in O(1) time by answering small interval rank queries.

(iv) We are on an edge of the suffix tree between a node u and some child u_j of u. In this case all occurrences of P[0..i-1] are followed by the same symbol a = P[i]. Hence all occurrences of $\overline{P[0..i-1]}$ are preceded by P[i] in the reverse text. Therefore $\overline{B}[l_{i-1}..r_{i-1}]$ contains only one symbol a = P[i]. In this case rank_a(r_{i-1}, \overline{B}) and rank_a($l_{i-1} - 1, \overline{B}$) are partial rank queries; hence l_i and r_i can be computed in O(1) time.

In all cases, except for the case (iia), we can answer rank queries and compute l_i and r_i in O(1) time. In case (iia) we need $O(\log \log \sigma)$ time answer rank queries. However case (iia) only takes place when the node u is heavy and its child u_a is light. Since all descendants of a light node are light, case (iia) occurs only once when the pattern P is processed. Hence the total time to find the range of \overline{P} in \overline{B} is $O(|P| + \log \log \sigma)$ time. When the range is known, we can count and report all occurrences of \overline{P} in standard way.

Construction Algorithm. We can construct the suffix tree \mathcal{T} and the BWT \overline{B} in O(n) deterministic time. Then we can visit all nodes of \mathcal{T} and identify all nodes u for which the data structure D_u must be constructed. We keep information about nodes for which D_u will be constructed in a bit vector. For every such node we also store the list of its heavy children with their labels. To compute additional information for D_u , we traverse the nodes of \mathcal{T} one more time using a variant of depth-first search. When a node $u \in \mathcal{T}$ is reached, we know the interval $[l_u, r_u]$ of $\overline{s_u}$ in \overline{B} , where s_u is the string that labels the path from the root to a node $u \in \mathcal{T}$. We generate the list of all children u_i of u and their respective labels a_i . If we store a data structure D_u for the node u, we identify labels a_h of heavy children u_h of u. For every a_h we compute rank $_{a_h}(l_u - 1, \overline{B})$ and rank $_{a_h}(r_u, \overline{B})$ and add this information to D_u . Then we generate the intervals that correspond to all strings $\overline{s_u a_i}$ in \overline{B} and keep them in a list List(u). Since intervals in List(u) are disjoint, we can store List(u) in $O(\sigma \log n)$ bits.

We can organize our traversal in such way that only $O(\log n)$ lists List(u) need to be stored. Let num(u) denote the number of leaves in the subtree of a node u. We say that a node is *small* if $num(u_i) \leq num(u)/2$ and big otherwise. Every node can have at most one big child. When a node u processed and List(u) is generated, we visit small children u_i of u in arbitrary order. When all small children u_i are visited and processed, we discard the list L(u). Finally if u has a big child u_b , we visit u_b . If a node u is not the root node and we keep List(u), then $num(u) \leq num(parent(u))/2$. Therefore we keep List(u) for at most $O(\log n)$ nodes u. Thus the space we need to store all List(u) is $O(\sigma \log^2 n) = o(n)$ for $\sigma \leq n^{1/2}$. Hence the total workspace used of our algorithm is $O(n \log \sigma)$. The total number of rank queries that we need to answer is O(n/d) because all D_u contain O(n/d) elements. We need $O((n/d) \log \log \sigma)$ time to construct all D_u and to answer all rank queries. The total time needed to traverse \mathcal{T} and collect necessary data about heavy nodes and special nodes is O(n). Therefore our index can be constructed in O(n) time.

It remains to show how we can store selected precomputed answers to rank queries in $O(\log \sigma)$ bits per query. We divide the sequence \overline{B} into chunks of size σ^2 . For each chunk and for every symbol a we encode the number of a's occurrences per chunk in a binary sequence A_a , $A_a = 1^{d_1}01^{d_2}0...1^{d_i}0...$ where d_i is equal to the number of times a occurs in the *i*-th chunk. If a symbol $\overline{B}[i]$ is in the chunk Ch, then we can answer $\operatorname{rank}_a(i,\overline{B})$ by O(1) queries on A_a and a rank query on Ch; see e.g., [19]. Suppose that we need to store a pre-computed answer to a query $\operatorname{rank}_a(i,\overline{B})$; we store the answer to $\operatorname{rank}_a(i',Ch)$ where Ch is the chunk that contains i and i' is the relative position of $\overline{B}[i]$ in Ch. Since a chunk contain σ^2 symbols, $\operatorname{rank}_a(i',Ch) \leq \sigma^2$ and we can store the answer to $\operatorname{rank}_a(i,\overline{B})$ in $O(\log \sigma)$ bits. When the answer to the rank query on Ch is known, we can compute the answer to $\operatorname{rank}_a(i,\overline{B})$ in O(1) time.